

# Frontiers of Network Science

## Fall 2023

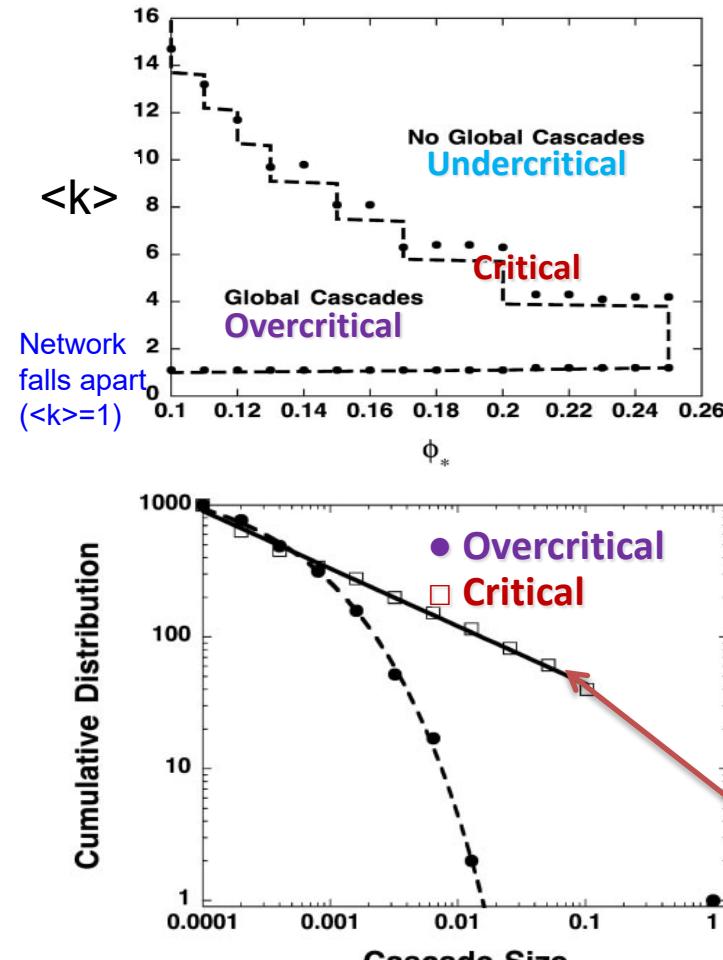
### Class 14 Robustness, the rest of it (Chapter 8 in Textbook)

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**Boleslaw Szymanski**

based on slides by  
Albert-László Barabási  
and Roberta Sinatra

# FAILURE PROPAGATION MODEL

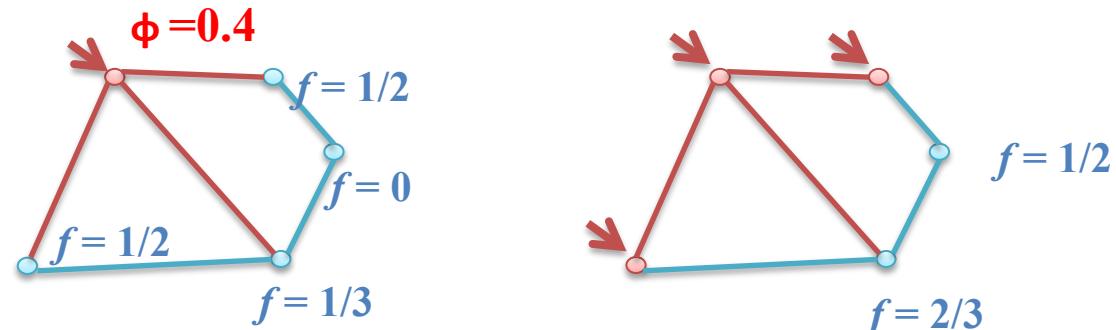


## Initial Setup

- Random graph with  $N$  nodes
- Initially each node is functional.

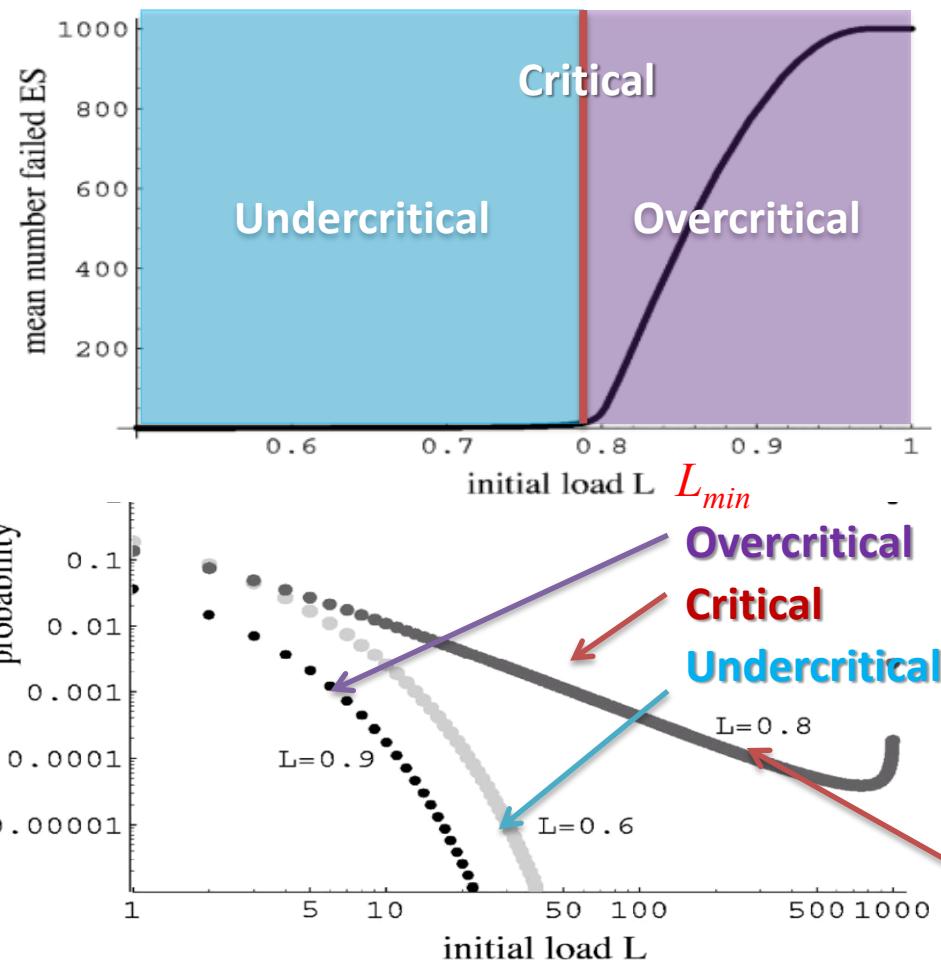
## Cascade

- Initiated by the failure of one node.
- $f_i$ : fraction of failed neighbors of node  $i$ . Node  $i$  fails if  $f_i$  is greater than a global threshold  $\phi$ .



Erdos-Renyi network  
 $P(S) \sim S^{-3/2}$

# OVERLOAD MODEL

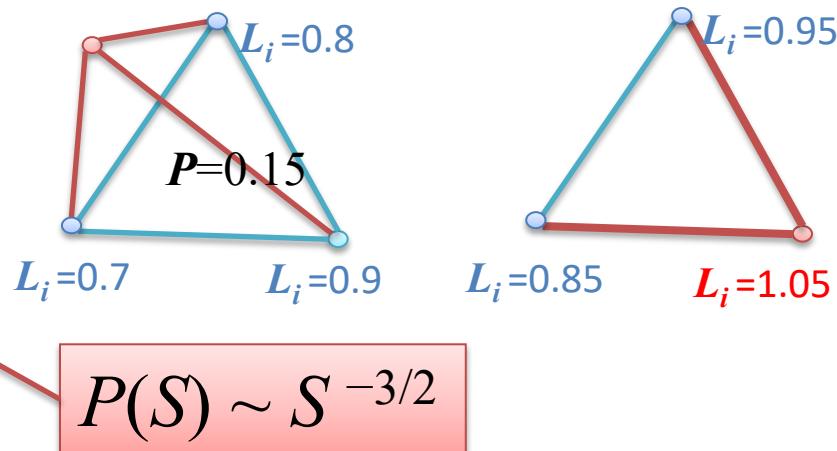


## Initial Conditions

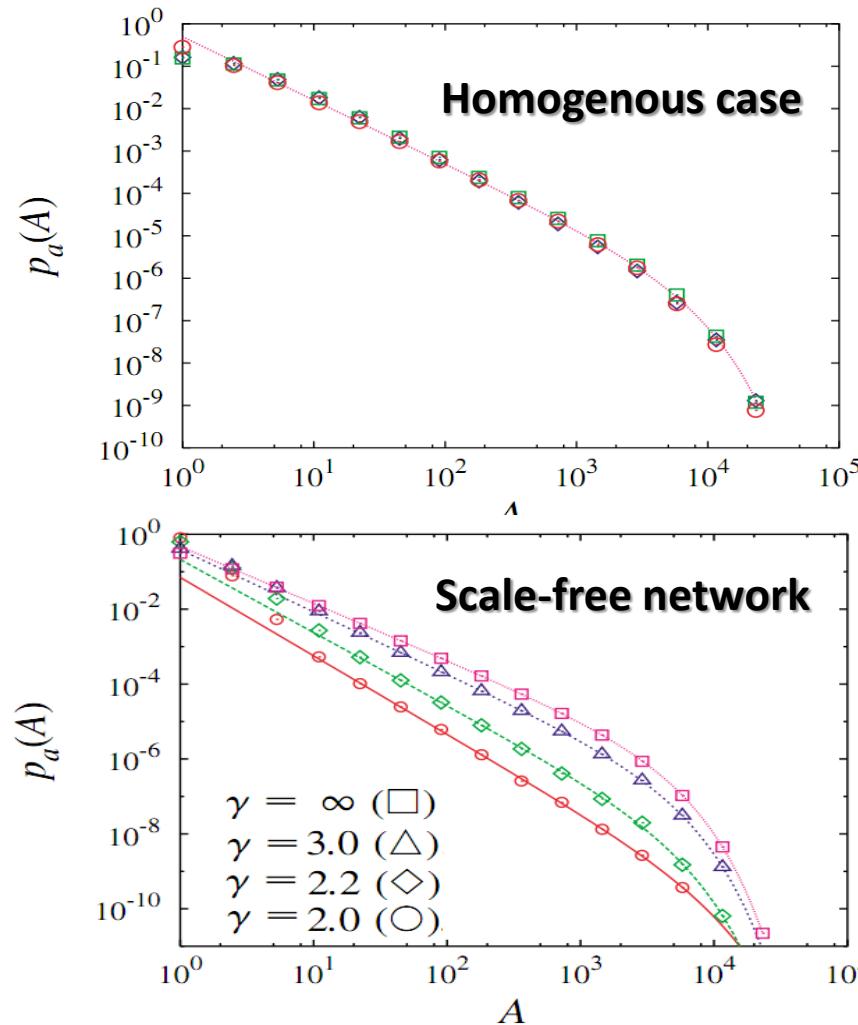
- $N$  Components (complete graph)
- Each component has random initial load  $L_i$  drawn at random uniformly from  $[L_{min}, 1]$ .

## Cascade

- Initiated by the failure of one component.
- Component fail when its load exceeds 1.
- When a component fails, a fixed amount  $P$  is transferred to all the rests.



# SELF-ORGANIZED CRITICALITY AKA SANDPILE MODEL



## Initial Setup

- Random graph with  $N$  nodes
- Each node  $i$  has height  $\mathbf{h}_i = \mathbf{0}$ .

## Cascade

- At each time step, a grain is added at a randomly chosen node  $i$ :  $\mathbf{h}_i \leftarrow \mathbf{h}_i + 1$
- If the height at the node  $i$  reaches a prescribed threshold  $\mathbf{z}_i = \mathbf{k}_i$ , then it becomes unstable and all the grains at the node topple to its adjacent nodes:  $\mathbf{h}_i = \mathbf{0}$  and  $\mathbf{h}_j \leftarrow \mathbf{h}_j + 1$
- if  $i$  and  $j$  are connected.

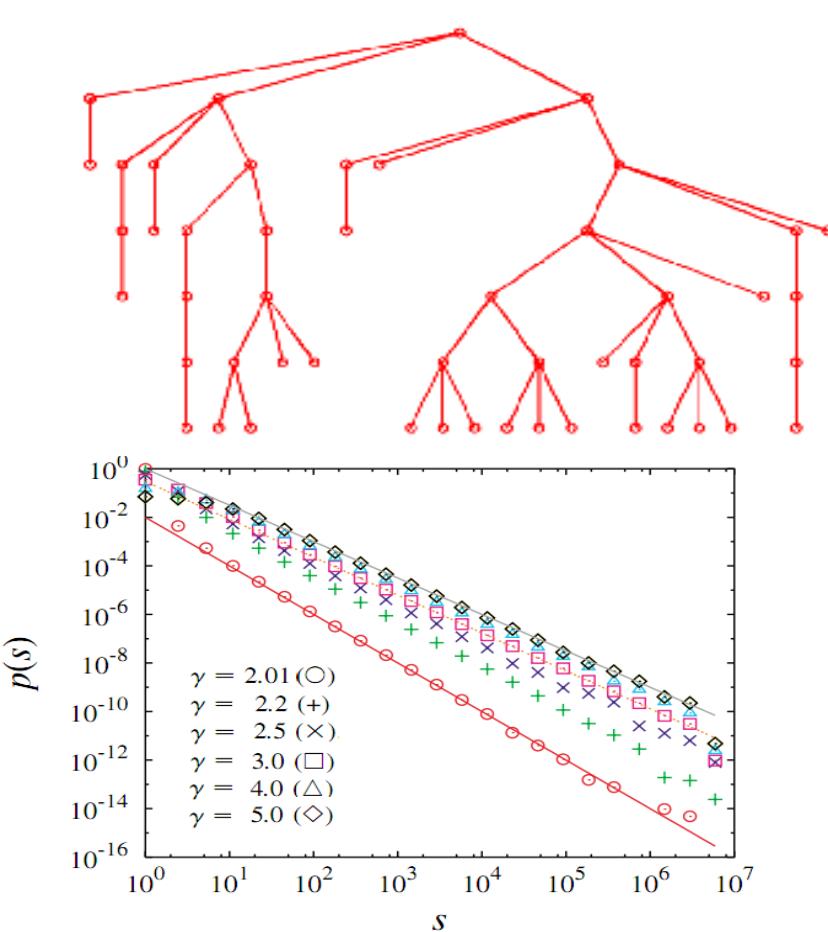
Homogenous network:  $\langle k^2 \rangle$  converges

$$P(S) \sim S^{-3/2}$$

Scale-free network :  $p_k \sim k^\gamma$  ( $2 < \gamma < 3$ )

$$P(S) \sim S^{-\gamma/(\gamma-1)}$$

# BRANCHING PROCESS MODEL



## Branching Process

Starting from a initial node, each node in generation  $t$  produces  $k$  number of offspring nodes in the next  $t + 1$  generation, where  $k$  is selected randomly from a fixed probability distribution  $q_k = p_{k-1}$ .

## Hypothesis

- No loops (tree structure)
- No correlation between branches

Fix  $\langle k \rangle = 1$  to be critical  $\rightarrow$  power law  $P(S)$

Narrow distribution:  $\langle k^2 \rangle$  converged

$$P(S) \sim S^{-3/2}$$

Fat tailed distribution:  $q_k \sim k^\gamma$  ( $2 < \gamma < 3$ )

$$P(S) \sim S^{-\gamma/(\gamma-1)}$$

## SHORT SUMMARY OF MODELS: UNIVERSALITY

Models	Networks	Exponents
Failure Propagation Model	ER	1.5
Overload Model	Complete Graph	1.5
BTW Sandpile Model	ER/SF	1.5 (ER) $\gamma/(\gamma - 1)$ (SF)
Branching Process Model	ER/SF	1.5 (ER) $\gamma/(\gamma - 1)$ (SF)

**Universal for homogenous networks**

$$P(S) \sim S^{-3/2}$$

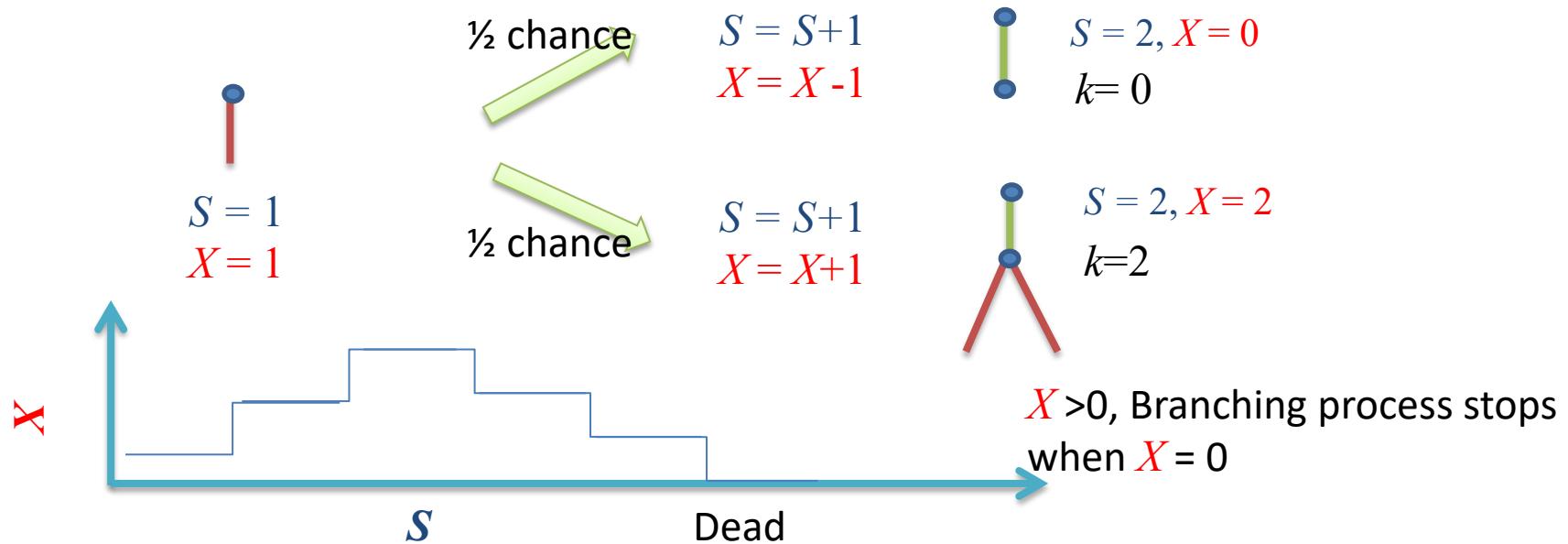
Same exponent for percolation too  
(random failure, attacking, etc.)

## EXPLANATION OF THE 3/2 UNIVERSALITY

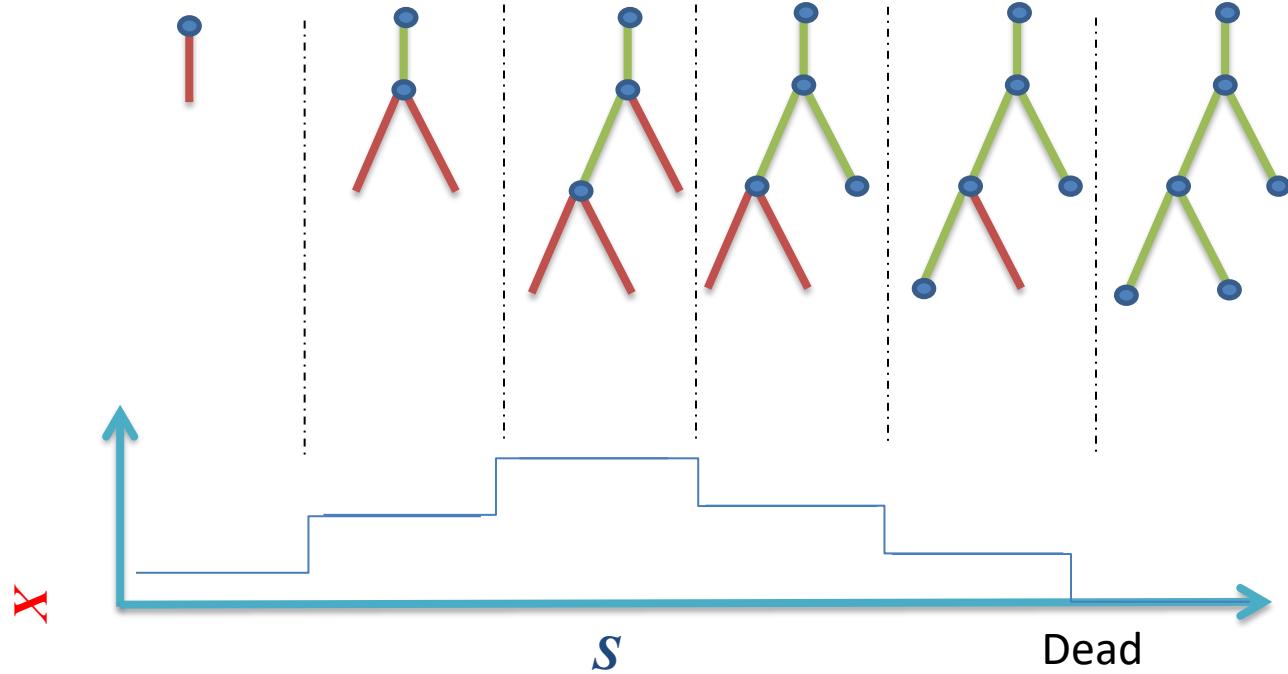
Simplest Case:  $q_0 = q_2 = 1/2$ ,  $\langle k \rangle = 1$

$S$ : number of nodes

$X$ : number of open branches



## EXPLANATION OF THE 3/2 UNIVERSALITY

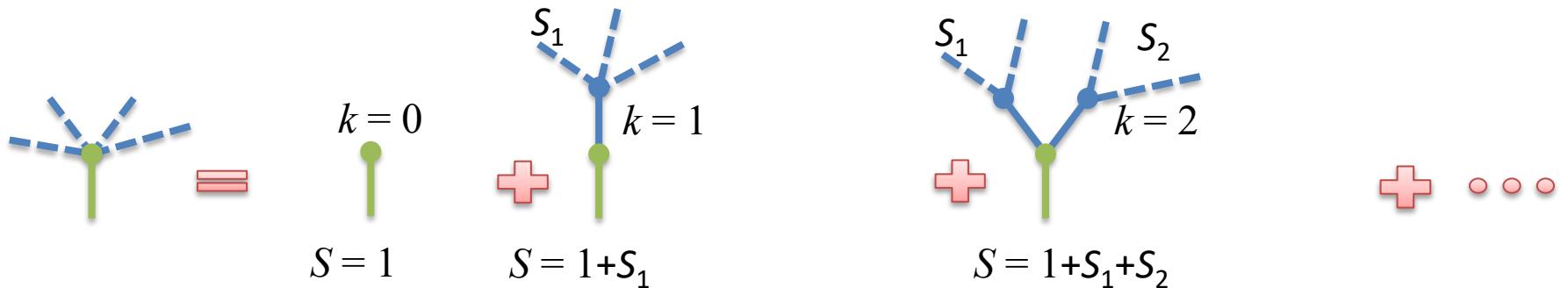


Equivalent to **1D random walk model**, where  $X$  and  $S$  are the position and time , respectively.

**Question:** what is the probability that  $X = 0$  after  $S$  steps?

**First return probability**  $\sim S^{-3/2}$

## SIZE DISTRIBUTION OF BRANCHING PROCESS (CAVITY METHOD)



$$P(S) = q_0 \delta(1) + q_1 \sum_{S_1} P(S_1) \delta(1 + S_1 - S) + q_2 \sum_{S_1, S_2} P(S_1) P(S_2) \delta(1 + S_1 + S_2 - S) + \dots$$

$$P(S) = \sum_k q_k \left( \sum_{S_1, \dots, S_k} P(S_1) P(S_2) \cdots P(S_k) \delta(1 + \sum_{j=1}^k S_j - S) \right)$$

# SOLVING THE EQUATION BY GENERATING FUNCTION

**Definition:**

$$G_S(x) = \sum_{S=0} P(S)x^S$$

$$G_k(x) = \sum_{k=0} q_k x^k$$

**Property:**

$$G_S(1) = G_k(1) = 1$$

$$G_S'(1) = \langle S \rangle, G_k'(1) = \langle k \rangle$$

$$P(S) = \sum_k q_k \left( \sum_{S_1, \dots, S_k} P(S_1)P(S_2) \cdots P(S_k) \delta\left(1 + \sum_{j=1}^k S_j - S\right) \right)$$

$$\begin{aligned} G_S(x) &= \sum_k q_k \left( \sum_{S_1, \dots, S_k} P(S_1) \cdots P(S_k) x^{1 + \sum_j S_j} \right) = \sum_k q_k x G_S(x)^k \\ &= x G_k(G_S(x)) \end{aligned}$$

**Phase Transition**

$$\langle S \rangle = G_S'(1) = 1 + G_k'(1) \quad G_S'(1) = 1 + \langle k \rangle \langle S \rangle, \text{ then}$$

$$\langle S \rangle = 1/(1 - \langle k \rangle)$$

The average size  $\langle S \rangle$  **diverges** at  $\langle k \rangle_c = 1$

## FINDING THE CRITICAL EXPONENT FROM EXPANSION

**Definition:**

$$G_S(x) = \sum_{S=0} P(S)x^S$$

$$G_k(x) = \sum_{k=0} q_k x^k$$

**Theorem:**

If  $P(k) \sim k^\gamma$  ( $2 < \gamma < 3$ ), then for  $\delta x < 0$ ,  $|\delta x| \ll 1$

$$G(1 + \delta x) = 1 + \langle k \rangle \delta x + \langle k(k-1)/2 \rangle (\delta x)^2 + \dots + O(|\delta x|^{\gamma-1})$$

$$P(S) \sim S^{-\alpha}, 1 < \alpha < 2$$

$$G_S(1 + \delta x) \approx 1 + A |\delta x|^{\alpha-1}$$

**Homogenous case:  $\langle k^2 \rangle$  converged**

$$\langle k \rangle = 1, \langle k^2 \rangle < \infty$$

$$G_k(1 + \delta x) \approx 1 + \delta x + B \delta x^2$$

**Inhomogeneous case:  $\langle k^2 \rangle$  diverged**

$$\langle k \rangle = 1, q_k \sim k^\gamma (2 < \gamma < 3)$$

$$G_k(1 + \delta x) \approx 1 + \delta x + B |\delta x|^{\gamma-1}$$

## CRITICAL EXPONENT FOR HOMOGENEOUS CASE

**Homogenous case**

$$G_k(1 + \delta x) \approx 1 + \delta x + B\delta x^2$$

$$G_S(1 + \delta x) \approx 1 + A|\delta x|^{\alpha-1}$$

$$G_S(x) = xG_k(G_S(x))$$

$$G_S(x) \approx 1 + A|\delta x|^{\alpha-1}$$

$$\begin{aligned} xG_k(G_S(x)) &\approx (1 + \delta x)[1 + (G_S(1 + \delta x) - 1) + B(G_S(1 + \delta x) - 1)^2] \\ &\approx (1 + \delta x)[1 + A|\delta x|^{\alpha-1} + AB|\delta x|^{2\alpha-2}] \\ &= 1 + A|\delta x|^{\alpha-1} + AB|\delta x|^{2\alpha-2} + \delta x + O(|\delta x|^\alpha) \end{aligned}$$

The **lowest** order reads  $AB|\delta x|^{2\alpha-2} + \delta x = 0$ , which requires  $2\alpha - 2 = 1$  and  $A = 1/B$ . Or,

$$\alpha = 3/2$$

## CRITICAL EXPONENT FOR INHOMOGENEOUS CASE

### Inhomogeneous case

$$G_k(1 + \delta x) \approx 1 + \delta x + B|\delta x|^{\gamma - 1}$$

$$G_S(1 + \delta x) \approx 1 + A|\delta x|^{\alpha - 1}$$

$$G_S(x) = xG_k(G_S(x))$$

$$G_S(x) \approx 1 + A|\delta x|^{\alpha - 1}$$

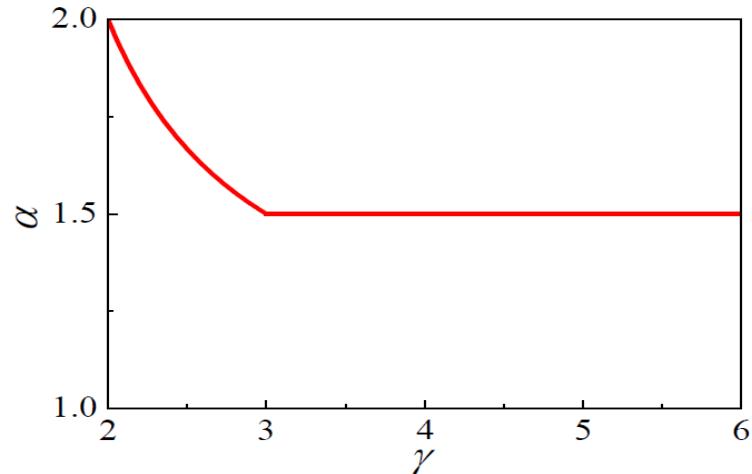
$$\begin{aligned} xG_k(G_S(x)) &\approx (1 + \delta x)[1 + (G_S(1 + \delta x) - 1) + B|G_S(1 + \delta x) - 1|^{\gamma - 1}] \\ &\approx (1 + \delta x)[1 + A|\delta x|^{\alpha - 1} + AB|\delta x|^{(\alpha - 1)(\gamma - 1)}] \\ &= 1 + A|\delta x|^{\alpha - 1} + AB|\delta x|^{(\alpha - 1)(\gamma - 1)} + \delta x + O(|\delta x|^\alpha) \end{aligned}$$

The **lowest** order reads  $AB|\delta x|^{(\alpha - 1)(\gamma - 1)} + \delta x = 0$ , which requires  $(\alpha - 1)(\gamma - 1) = 1$  and  $A = 1/B$ . Or,

$$\alpha = \gamma / (\gamma - 1)$$

## COMPARING THE PREDICTION WITH THE REAL DATA

$$P(S) \sim S^{-\alpha}, \alpha = \begin{cases} 3/2, & \gamma > 3 \\ \gamma/(\gamma-1), & 2 < \gamma < 3 \end{cases}$$



### Blackout

Source	Exponent	Quantity
North America	2.0	Power
Sweden	1.6	Energy
Norway	1.7	Power
New Zealand	1.6	Energy
China	1.8	Energy

Earthquake  $\alpha \approx 1.67$

I. Dobson, B. A. Carreras, V. E. Lynch, D. E. Newman, *CHAOS* **17**, 026103 (2007)

Y. Y. Kagan, *Phys. Earth Planet. Inter.* **135** (2–3), 173–209 (2003)